National Aeronautics and Space Administration

Satellite Servicing Technology Development

30 May 2012 OCT Rev. A

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 Mason Peck asked me to represent OCT at today's workshop.

Theme

• Ben Reed asked me to address the "How?" aspects of satellite servicing.

 These are a natural fit, focusing on technologies for robotic satellite servicing.

How have we done satellite servicing in the past?

Satellite Servicing History and Present

• NASA

- 1984: Solar Max Capture, Repair and Re Deploy
- 1992: Intelsat VI Capture and Re Deploy
- 1993: Hubble Repair, Servicing Missions 1-4
- 2004: Demo of Autonomous Rend. Tech.
- 2011: DARPA/OCT Manned Geo Servicing Study
- 2012: Robotic Refueling Mission on ISS
- 2012: Robonaut 2 Task Board on ISS
- Other US Agencies
 - 2004: Air Force XSS 10 and 11
 - 2007: DARPA Orbital Express
- Other Countries
 - 1997: NASDA ETS-VI Rendezvous and robotics



STS-49 Intelsat VI 1992









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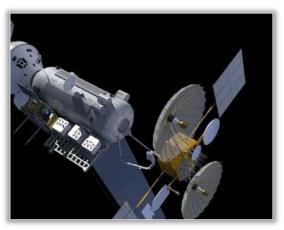


- NASA Technology Roadmaps (Under Review by NRC)
 - Tech Area 2, In-Space Propulsion Technologies
 - Upper Stages, Transfer Missions, Tethers, Beyond Chemical Fuel
 - Tech Area 4, Robotics, Tele-Robotics and Autonomous Systems
 - Autonomous Rendezvous and Docking, Grappling, Berthing, Servicing Manipulation, Sensing and Perception, Inspection, Repair
 - Tech Area 5, Communication and Navigation
 - Position, Navigation and Timing, GPS, Relative Proximity Navigation
- Development Approaches
 - NASA will continue collaboration with industry, and other agencies and organizations
 - Where possible we use lab, facility and analog testing of approaches
 - We utilize the ISS for technology demonstrations with diverse vehicles

Robotic Servicing Functions (LEO, GEO and Beyond)

- Inspection
 - External, In Structure
- Relocation
 - Solve Launch Failure, End of Mission
- Resolve Deployment Failure
 - Antennae, Solar Array, Mechanisms
- Refuel
 - Handle Connectors and Hoses
- Add Components
 - De-Orbit stages, new Elements
- Swap Robot Compatible Parts
 - Instruments, Batteries
- Dexterous Manipulation
 - Non Robot Compatible Tasks, Contingency













Robotic Servicing Functions: Inspection

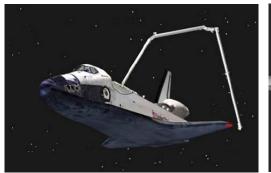


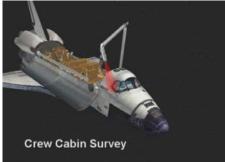
• Free Flying Inspection





Manipulator Inspection Wand





• New Inspection Technologies





Robotic Servicing Functions: Refueling

• Orbital Express Refueling Mission

ISS Robotic Refueling Mission Demo

Robotic Servicing Functions: Dexterous Manipulation

Hubble Servicing Experiments

ISS Robonaut Plans



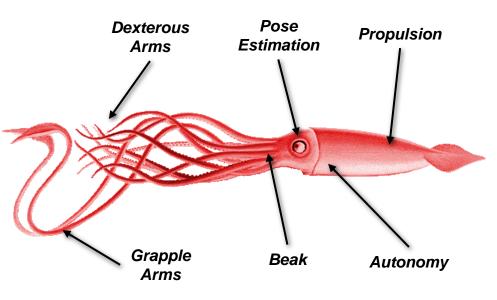
How would "Mother Nature" do satellite servicing?

Exploration Robotics Servicing

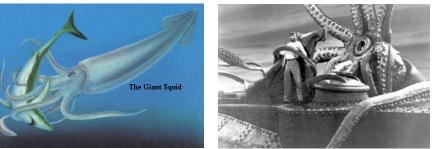
NASA

- Squid Design
 - Neutral Buoyancy Specialist
 - 6 Axis Thrust Control
 - Long Reach Grapple Arms
 - Dexterous Work Arms
 - Beak for Final "Docking"
 - Eye for Rendezvous/Prox Ops
 - Fully Autonomous Control
- Squid Tactics and Prey
 - Neutral Buoyancy Pursuit
 - Non Cooperative Targets
 - Grapple, Manipulate, Bite

Mother Nature's Solution: Giant Squid



Non cooperative Targets (Fact and Fiction)

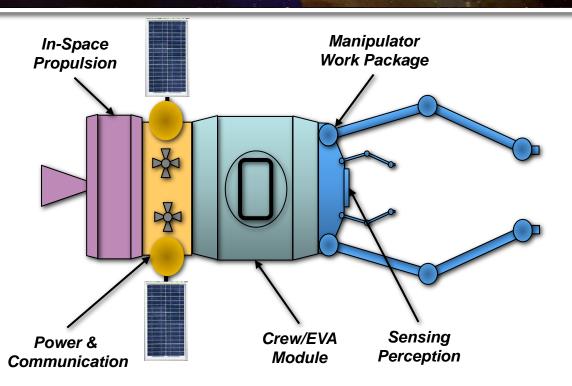


For exploration capability we need the ability to capture, control, and manipulate in space for servicing, assembly, and mobility

Engineering Solution: Building Block Approach

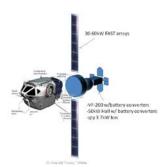


- Manipulator Work Package
 - Long Reach Grapple Arms
 - Dexterous Work Arms
 - Docking Fixtures/Decks
- Sensing and Perception
 - Long to Short Range
 - 6 Axis Pose Estimation
- Communication
 - In-Space Assets
 - To Earth
- Power
 - Solar Arrays
 - Batteries
- In-Space Propulsion
 - Upper Stage
 - RCS
- Pressurized Human Modules
 - Living Quarters/Protection
 - Command and Control
 - EVA Suit Ports/Locks









Technologies Transcend Single Missions

- Key Space Technologies
 - In-Space Propulsion
 - Robotic Manipulation
 - Rendezvous and Docking
 - Sensing and Perception
 - Navigation
- Technology Applications
 - ISS caretaking and utilization
 - Satellite servicing
 - Orbital debris removal
 - Deep space vehicle stack assembly
 - Telescope assembly

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